

LASER AIM SCORING SYSTEM

BACKGROUND OF THE INVENTION

1. Field of the Invention

The invention relates to training equipment for use with laser-guided weapons including bombs, rockets and artillery shells.

2. Description of Prior Art

There is a large stockpile in the military inventory of laser-guided munitions. To insure that the services achieve maximum effect from such weapons requires a sophisticated training program. Available training facilities include ground based electronic training stations, field training using Multiple Integrated Laser Engagement System (MILES) type system, which employs a laser version of the old game called "Tag", and field training using "live" training rounds. The use of ground based electronic stations, while useful for introductory training, is not the preferred method. Field training is a far more effective method. For MILES training systems, however, target ranges are limited to 3 kilometers or less because of output power limitations with state-of-the-art laser diodes. There are also problems with bore sighting of the existing

MILES training systems. Field training using live training rounds, while the preferred method, is extremely limited, due to the expense and availability of the training rounds.

There is a need for an improved system of training designator operators under more realistic field conditions. As an example, for the Army Apache aircraft platform, gunners are tasked to designate targets for the laser guided Hellfire missile system. Because retrofit of the aircraft with MILES equipment is time consuming, and has performance characteristics not matching the tactical laser, it is not frequently used. Currently, training and scoring of Apache gunners is done after the training exercise using videotape from the weapons system. This delayed feedback to the gunner degrades training effectiveness.

#### SUMMARY OF THE INVENTION

This invention enables real time simulation and feedback to the gunner by adding a "smart" hardware interface to the pop-up targets as found on military firing ranges. The target, typically a silhouette painted on plywood, is attached to a target pop-up device. A downrange programmable microprocessor with laser sensors and video camera is located near, and interfaced to the pop-up device. The sensors include both on-target and off-target detectors that sense laser radiation at the designator frequency. If mission requirements are met (i.e. proper designator code, laser time off-target, laser time on-target), the target pop-up device is commanded to drop the target, signifying a "hit". The gunner, following proper engagement procedures, would instantly see the target drop at the proper round impact time. For added realism, the system can also command the Hoffman Target Kill Simulator to fire, adding the

effects of fire and smoke to the training engagement. This fire and smoke can be seen by both the optical day sight and the thermal night sight.

A radio modem links the downrange microprocessor, laser sensors, and video camera to a personal computer (PC) located in the range control tower. The video camera is near infrared enhanced, enabling the control tower operator to view, on a video monitor, both the target and the moving laser spot on the target. The tower operator remotely operates and programs the downrange target equipment set via a menu driven software interface. Prior to a training engagement, the tower operator can verify operation of the downrange equipment set by raising and lowering the target, and test firing the Hoffman device. During a training engagement, the tower operator monitors the event, and programs the downrange microprocessor with the proper training scenario.

#### BRIEF DESCRIPTION OF THE DRAWINGS

The foregoing and other objects, aspects and advantages will be better understood from the following detailed description of a preferred embodiment of the invention with reference to the drawings, in which similar characters refer to similar parts, and in which:

FIG. 1 is a pictorial view of a complete Laser Aim Scoring System (LASS) including a pop-up target with an electronic target monitor linked to a remote video monitor in a control tower.

FIG. 2 is an isometric view of the target monitor.

## WRITTEN DESCRIPTION OF THE PREFERRED EMBODIMENT

Referring to Fig. 1, there is shown a complete layout of the operating system of the present invention. The system operates on the principle that the success of the target engagement is directly related to the ability of the laser designator operator (the gunner) to properly aim the laser, near or on the target, at appropriate times during the flight of the missile. The drawing portrays a helicopter 10 or flying platform, which usually involves autonomous designations, i.e. the same platform both designates the target and launches the laser-guided munitions. The same concept can involve ground-based designators and ground based munitions. The system also supports buddy lasing, where either a ground gunner or air platform designates the target, or another platform launches the weapon. The target 11 is a flat pop-up board painted to provide the same contrast with the background, as would a real target. An active test monitor 12 is placed in front of the target far enough away and low enough to not intercept the laser beam that a gunner uses to project a signature on the target. This test monitor has a lower on-target section 13 that detects laser reflections from the target within the circular area 13a. There is also a separate upper off-target section 14 that detects weaker laser reflections above below or to either side of the target. For convenience in disassembly, fastening strips such as those that incorporate a Velcro® material join the two sections.

Referring briefly to FIG. 2, the lower section 13 contains an on-target detector behind lens 20 and a video camera behind lens 21, both of which image the whole target on their focal planes. The upper section 14 contains an array of four very sensitive offset detectors behind lenses 22-25. These offset detectors cover a field of view within approximately two steradians

adjacent to the target for offset laser energy. Lens 22 gathers light above the target, lens 24 gathers light in front of the target and lenses 23 and 25 gather light on either side of the target. Each detector, in either opaque housing 26 or 27, may comprise at least one photodiode or a photo-cathode with an electron multiplier in the focal plane of its lens. The lenses and housings may be specific to the detectors as shown or shared with other detectors. Threshold sensitivity for the offset detectors is set very low, so that they respond to laser designator ground scatter of a beam hitting the ground anywhere within approximately 100 - 200 meters of the target. The on-target detector covers only the field of view of the target for on-target laser energy. The threshold sensitivity for this detector is set much higher, so that it will respond only to lambertian scatter directly off the target. The detectors are preferably narrow-band diodes designed for predetermined infrared wavelengths.

Returning to FIG. 1, the above test monitor is shown connected to a LASS microprocessor 15, preferably by direct wiring, so that it supplies a time base for each test and computes the relative outputs of the detectors with time. It also computes a dwell time for the detectors that is weighted on their distance from the center of the target at any given time. When the computer detects a successful designation it sends a firing signal to a squib in a Hoffman Kill Simulator 16, which is an off-the-shelf pyrotechnic device that creates smoke, elevated light flashes and a loud noise for the gunner's benefit.

The system further includes a tower computer 19a with a normal monitor 19b and a passive video monitor 19c, which is usually located in a control tower overlooking the target range at a safe distance, so as to permit live munitions tests when needed. This computer and

passive video monitor may be hard wired, but preferably receives data from the LASS microprocessor 15 by means of a modulated RF transmitter antenna 17 near the central processor and an RF detector antenna 18 in the tower. The LASS central processor is hard wired to the popup target controller. The antennas provide a video link and a separate data link on different carrier frequencies. The video link is demodulated by an RF Video Receiver and wired to the passive video monitor to show the picture from the video camera behind lens 21. The data link is demodulated by an RF data modem 19e that is hard wired to the remote computer 19a. The remote computer records the test data for comparison studies and individual gunner ratings.

The current version of LASS sends a signal to the target lifter and to the Hoffman Kill Simulator 16 in place of the signal that would be sent in live fire training in response to a hit detection by an existing target piezoelectric hit sensor on the target. Until now, when a ballistic round hits the target board, e.g. a bullet, the impact causes the piezoelectric hit sensor mounted on the target board to "ring" voltaically. This ringing effect is detected by the target lifter device and is interpreted by the range control instrumentation as a hit, and the target board dropped. Since most Hellfire training is done without actual Hellfire training rounds, these simulated engagements cannot result in piezoelectric hit detection. Instead, the LASS target suite scores the proper employment of the laser designator for offset and on-target lasing. If LASS determines a hit, it mimics the operation of a piezoelectric hit sensor, and forces the target to drop. The dropping of the target provides a visual, real time feedback to the gunner that the engagement was scored as a hit.

The training method for testing a gunner's ability to designate a target, near a control tower, with a given laser, at an impact point for a projectile seeking said designated target with a sensor for only the narrow band radiation from said given laser, includes the following steps:

[A] placing a substantially two dimensional representation of the target on a mechanism that pops the target upward to a nearly vertical (with respect to the ground plane) position or downward to a nearly horizontal position in response to an electric signal from the tower;

[B] directing a first array of high sensitivity offset sensors for the narrow band radiation toward the target and an area of ground within at least 100 meters therefrom in response to a gunner's cue signal;

[C] directing a video camera and a second array of low sensitivity sensors for the narrow band radiation only toward the space occupied by the target, when in the nearly vertical position, in response to the same cue signal;

[D] loading software into the microprocessor that defines the training scenario and proper timing for off-target and on-target lasing, and correct designator coding for a successful laser designator engagement (illumination of the area around the target and finally the target itself);

[E] transporting the gunner and given laser toward and within missile range of the target;

[F] generating the cue signal from the gunner to the tower to indicate a launch time for the missile;

[G] generating the signal from the tower to the target in response to the cue signal;

[H] feeding the actual sensor outputs to microprocessor;

[I] generating a score, in the microprocessor, based on the actual sensor outputs as a function of time as compared to the required sensor outputs;

[J] computing the time of expected missile impact at the target from the launch time in the microprocessor;

[K] generating the electric signal in the control tower, if the score exceeds a preselected hit threshold;

[L] generating an electric hit signal in the microprocessor if the electric signal of step [K] has been generated at the time of impact;

[M] transmitting the hit signal, if present, to the target raising/lowering mechanism to lower the target in the event that a hit is scored;

[N] transmitting the hit signal, if present, to a hit simulator in the form of an electrical squib, whereby the hit signal fires the squib to generate smoke and light signals visible for the subject and anyone in the control tower;

[O] storing the output signal from the video camera, as well as the computed and actual sensor output values in the computer in the control tower;

[P] clearing the microprocessor for a new test; and

[Q] generating an electric signal to raise the target board if hit signals were generated in steps [K] and [L] resulting in lowering the target board in step [M].

The gunner initially aims the laser at a point far enough from the target to avoid enemy detection but close enough to keep the missile on its path. Finally the target itself is illuminated long enough to let the missile make last minute corrections for a direct hit. The control tower equipment permanently stores the transmitted data. The scoring information can be saved on computer disk for later after action briefings, or noted in a logbook. The target video, showing

size and location of the laser spot on the target, can be displayed on a passive monitor in the control tower during the test and also recorded for after action briefings.

While this invention has been described in terms of a preferred embodiment consisting of a particular test system and method of using same, is fully capable of obtaining the objects and providing the advantages above stated, it is to be understood that the presently preferred embodiments are merely illustrative of the invention. As such, no limitations are intended other than as defined in the appended claims.